

GSEOS Driver for ROSETTA

Revision 1.4

IDA-GSEOS-0007

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Prepared by
Kai Stoeckner

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1 Scope

1.1 Purpose of this Document

Purpose of this document is to describe the GSEOS driver that is used for the Project ROSETTA. The driver is a Windows NT Kernel mode driver named **GseRoset.sys**.

1.2 Change Record

Table 1 Change Record

Date	Revision	Author	Affected Sections
6/7/1999	1.0	Stoeckner	All sections
6/7/1999	1.1	Stoeckner	5
6/15/1999	1.2	Stoeckner	4.1
1/13/2000	1.3	Stoeckner	1.4, 2, 3.8, 3.9, 4.1
8/1/2000	1.4	Stoeckner	Sensim added, 1.4, 2, 3.12, 3.13, 3.12

1.3 Reference Documentation

All GSEOS related documents are listed in the GSEOS Document Index IDA-GSEOS-0000.

1.4 Abbreviations

Table 2 Abbreviations

EGSE	<u>E</u> lectrical <u>G</u> round <u>S</u> upport <u>E</u> quipment
FESIM	<u>F</u> ront- <u>E</u> nd <u>S</u> imulator
GSEOS	<u>G</u> round <u>S</u> upport <u>E</u> quipment <u>O</u> perating <u>S</u> ystem
MCB	<u>M</u> echanism <u>C</u> ontroller <u>B</u> oard
MGSE	<u>M</u> echanical <u>G</u> round <u>S</u> upport <u>E</u> quipment
NAC	<u>N</u> arrow <u>A</u> ngle <u>C</u> amera
PCM	<u>P</u> ower <u>C</u> ontroller <u>M</u> odule

RTL	<u>R</u> untime <u>L</u> ibrary
ROSETTA	Mission named after the Rosetta Stone
ROSINA	<u>R</u> OSETTA <u>O</u> rbiter <u>S</u> pectrometer for <u>I</u> on and <u>N</u> eutral <u>A</u> nalysis
OSIRIS	<u>O</u> ptical, <u>S</u> pectroscopic, and <u>I</u> nfrared <u>R</u> emote <u>I</u> maging <u>S</u> ystem
SCSIM	<u>S</u> / <u>C</u> <u>S</u> imulator
SENSIM	ROSINA <u>S</u> ensor <u>S</u> imulator
WAC	<u>W</u> ide <u>A</u> ngle <u>C</u> amera

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2 Introduction

The GSEOS 4.0 is a program designed to run under Windows NT. Under Windows NT there is for a user program no way to access the hardware directly. The program needs a kernel mode driver. Only a kernel mode driver may serve interrupts and access hardware directly.

The driver for the project ROSETTA is **GseRoset.sys**. The file **GseRoset.g** contains all necessary configuration for an easy access to all driver functions and generated blocks via the GSEOS language. This file should be included in the project main configuration file.

The driver is able to generate GSEOS blocks and to process GSEOS commands. The blocks and commands are described in the next chapters.

For project ROSETTA the driver supports several hardware units:

Table 3 Supported Hardware

H/W Name	Description
TIF	A test I/F for the ISA bus. Used by IDA as test hardware for GSEOS and driver development and for performance measuring.
ATIF	An advanced test I/F for the PCI bus without busmaster. Used by IDA as test hardware for GSEOS and driver development and for performance measuring.
BTIF	A busmaster test I/F for the PCI bus. Used by IDA as test hardware for GSEOS and driver development and for performance measuring.
SCSIM	The spacecraft simulator for the instruments OSIRIS and ROSINA (S/C telemetry and 1355 I/F).
FESIM0	The front-end simulator for the instrument OSIRIS (NAC and PCM I/F).
FESIM1	The front-end simulator for the instrument OSIRIS (WAC and MCB I/F).
SENSIM	Sensor Simulator for ROSINA (instruments DFMS, RTOF, and COPS)

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3 Driver Generated Blocks

This section describes the various driver-generated blocks. The user should not change the names and the structure of the blocks. The usual way to use a driver-generated block is to write a decoder attached to the block.

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3.1 SelfStimulationTicker

Description The driver sends the block **SelfStimulationTicker** if the self-stimulation of the driver is enabled. The user may enable/disable the self-stimulation and change the interval in the Control Panel for the H/W driver in the GSEOS. The block may be used for debugging purposes.

Declaration

```
typedef struct
{
    ULONG ul;
} tsLong;
```

Definition `blockdef tsLong tblkSelfStimulationTicker SelfStimulationTicker;`

Example

```
decode on (SelfStimulationTicker)
{
    tblkTest TestNew;

    TestNew = Test;
    TestNew.ulSelfStimulationTickerDecoded =
        SelfStimulationTicker.ul * 2;

    send (TestNew);
}
```


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3.2 `_TIF`

Description The driver sends the TIF (Test I/F, ISA) generated data in the block `_TIF`.

Declaration

```
typedef union
{
    BITMAP 16 [32, 64] bmp;           // picture like [x, y]
    USHORT ausRaw[64][32];          // C like [y][x]
} tsTIF;
```

Definition `blockdef tsTIF tblkTIF _TIF;`

Example

```
decode on (_TIF)
{
    tblkTest TestNew;

    TestNew = Test;
    TestNew.ulTifCnt = Test.ulTifCnt + 1;

    send (TestNew);
}
```

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3.3 _ATIF

Description The driver sends the ATIF (Advanced Test I/F, PCI) generated data in the block _ATIF.

Declaration

```
typedef union
{
    BITMAP 32 [128, 128] bmp;        // picture like [x, y]
    ULONG  aulRaw[128][128];        // C like [y][x]
}
```

Definition `blockdef tsATIF tblkATIF _ATIF;`

Example

```
decode on (_ATIF)
{
    tblkTest TestNew;

    TestNew = Test;
    TestNew.ulAtifCnt = Test.ulAtifCnt + 1;

    send (TestNew);
}
```

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3.4 _BTIF

Description The driver sends the BTIF (Busmaster Test I/F, PCI) generated data in the block _BTIF.

Declaration

```
typedef union
{
    BITMAP 32 [128, 256] bmp;           // picture like [x, y]
    ULONG  aulRaw[256][128];          // C like [y][x]
} tsBTIF;
```

Definition `blockdef tsBTIF tblkBTIF _BTIF;`

Example

```
decode on (_BTIF)
{
    tblkTest TestNew;

    TestNew = Test;
    TestNew.ulBtifCnt = Test.ulBtifCnt + 1;

    send (TestNew);
}
```

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3.5 `_ScsimStatus`

Description The driver sends after the command `ScsimSendStatus` the SCSI status in the block `_ScsimStatus`.

Declaration

```
typedef struct
{
    ULONG aulRegFpga[9];
    ULONG aulRegCia[16];
    ULONG ulSciCmdCnt;
    ULONG ulSciCmdErrCnt;
    ULONG ulSciCmdErrStop;
    ULONG ulSciCmdErrMlc;
    ULONG ulSciCmdErrMls;
    ULONG ulSciCmdErrSck;
    ULONG bIsSciTlmActive;
    ULONG ulSciTlmErrCnt;
    ULONG ul1355TransmitCnt;
    ULONG ul1355ReceiveCnt;
    BOOL bIs1355TransmitActive;
} tsScsimStatus;
```

Definition `blockdef tsScsimStatus tblkScsimStatus _ScsimStatus;`

Example

```
decode on (_ScsimStatus)
{
    tblkTest TestNew;

    TestNew = Test;
    TestNew.ulScsimStatusCnt = Test.ulScsimStatusCnt + 1;

    send (TestNew);
}
```

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3.6 `_Scsim1355ReadFifo`

Description The driver sends received data on the 1355 bus in the block `_Scsim1355ReadFifo`.

Declaration

```
typedef struct
{
    ULONG aul[32768];
} tsScsim1355ReadFifo;
```

Definition

```
blockdef tsScsim1355ReadFifo tblkScsim1355ReadFifo
    _Scsim1355ReadFifo;
```

Example

```
// see block _Scsim1355EopFifo
```

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3.7 _Scsim1355EopFifo

Description The driver sends packet identifier of the received data on the 1355 bus in the block _Scsim1355EopFifo.

Declaration

```
typedef struct
{
    ULONG aul[10923];
} tsScsim1355EopFifo;
```

Definition

```
blockdef tsScsim1355EopFifo tblkScsim1355EopFifo
    _Scsim1355EopFifo;
```

Example

```
decode on (_Scsim1355EopFifo)
{
    tblkScsim1355ReadData Data;
    tblkScsim1355EopData Eop;
    ULONG i, j, ulDataElementCount, ulEopElementCount;

    Data = _Scsim1355ReadFifo;
    Eop = _Scsim1355EopFifo;
    ulDataElementCount = sizeof (_Scsim1355ReadFifo.aul) /
        sizeof (_Scsim1355ReadFifo.aul[0]);
    ulEopElementCount = sizeof (_Scsim1355EopFifo.aul) /
        sizeof (_Scsim1355EopFifo.aul[0]);

    for (i = 0; i < ulEopElementCount; i = i + 1)
    {
        ULONG ulEop, ulIdx;
        ulEop = Eop.aul[i];
        ulIdx = ulEop & 0x3FFF;

        // h/w error ?
        if (ulIdx >= ulDataElementCount)
            break;

        // mark eop and count packets
        if (ulEop & (1 << 16))
        {
            tblkScsim1355PacketReceiveCnt PacketCnt;

            Data.aul[ulIdx] = 0xFFFFFFFF;
            PacketCnt = Scsim1355PacketReceiveCnt;
            PacketCnt.ul = PacketCnt.ul + 1;
            send (PacketCnt);
        }

        // set slack space to 0
        if (ulEop & (1 << 15))
        {
            for (j = ulIdx; j < ulDataElementCount; j = j + 1)
                Data.aul[j] = 0;
            break;
        }
    }
    send (Data);
    send (Eop);
}
```

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3.8 _ScsimSciTlm

Description The driver sends incoming data on the SCSI S/C telemetry I/F in the block _ScsimSciTlm.

Declaration

```
typedef struct
{
    ULONG ulLength;
    UCHAR ucSync;
    UCHAR auc[16 * 1024 - sizeof (ULONG) - sizeof (UCHAR)];
} tsScsimSciTlm;
```

Definition blockdef tsScsimSciTlm tblkScsimSciTlm _ScsimSciTlm;

Example

```
decode on (_ScsimSciTlm)
{
    tblkScsimSciTlmCnt Counter;

    // HK marker: 0xEB
    if (_ScsimSciTlm.auc[2] == 0xEB)
    {
        tblkScsimSciHkData HkData;

        HkData = _ScsimSciTlm;
        send (HkData);
    }
    else
    {
        tblkScsimSciTlmData TlmData;

        TlmData = _ScsimSciTlm;
        send (TlmData);
    }

    // telemetry counter
    Counter.ul = ScsimSciTlmCnt.ul + 1;
    send (Counter);
}
```

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3.9 FesimStatus

Description The driver sends after the command FesimSendStatus the FESIM status in the block **FesimStatus**.

Declaration

```
typedef struct
{
    ULONG ulHw;
    ULONG aulReg[4];
    ULONG ulNWHkCnt;
    ULONG ulNWHkErrCnt;
    ULONG ulNWCmdCnt;
    ULONG ulNWCmdErrCnt;
    ULONG ulNWCmdRstCnt;
    ULONG ulPMHkCnt;
    ULONG ulPMCcmdCnt;
    ULONG ulPMCcmdErrCnt;
    ULONG ulPMCcmdRstCnt;
    ULONG ulCrbImgErrCnt;
    BOOL bIsNWCmdActive;
    BOOL bIsPMCcmdActive;
    ULONG ulCrbImgFullErrCnt;
} tsFesimStatus;
```


Definition `blockdef tsFesimStatus tblkFesimStatus FesimStatus;`

Example

```
decode on (FesimStatus)
{
    tblkTest TestNew;

    TestNew = Test;
    TestNew.ulFesimStatusCnt = Test.ulFesimStatusCnt + 1;

    send (TestNew);
}
```


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3.10 _FesimNWCmd

Description The driver sends incoming NAC/WAC command data from FESIM in the block _FesimNWCmd.

Declaration

```
typedef struct
{
    ULONG ulHw;
    ULONG ulLength;
    ULONG auc[512];
} tsFesimCmd;
```

Definition blockdef tsFesimCmd tblkFesimNWCmd _FesimNWCmd

Example

```
decode on (_FesimNWCmd)
{
    if (_FesimNWCmd.ulHw == 0)
    {
        tblkFesimNacCmd s;

        s = _FesimNWCmd;
        send (s);
    }
    else
    {
        if (_FesimNWCmd.ulHw == 1)
        {
            tblkFesimWacCmd s;

            s = _FesimNWCmd;
            send (s);
        }
    }
}
```

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3.11 _FesimPMCmd

Description The driver sends incoming PCM/MCB command data from FESIM in the block _FesimPMCmd.

Declaration

```
typedef struct
{
    ULONG ulHw;
    ULONG ulLength;
    ULONG auc[512];
} tsFesimCmd;
```

Definition `blockdef tsFesimCmd tblkFesimPMCmd _FesimPMCmd`

Example

```
decode on (_FesimPMCmd)
{
    if (_FesimPMCmd.ulHw == 0)
    {
        tblkFesimPcmCmd s;

        s = _FesimPMCmd;
        send (s);
    }
    else
    {
        if (_FesimPMCmd.ulHw == 1)
        {
            tblkFesimMcbCmd s;

            s = _FesimPMCmd;
            send (s);
        }
    }
}
```

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3.12 SensimStatus

Description The driver sends after the command SensimSendStatus the SENSIM status in the block SensimStatus.

Declaration `typedef struct`
 `{`
 `ULONG aulReg[35];`
 `} tsSensimStatus;`

Definition `blockdef tsSensimStatus tblkSensimStatus _SensimStatus;`

Example `decode on (_SensimStatus)`
 `{`
 `tblkTest TestNew;`

 `TestNew = Test;`
 `TestNew.ulSensimStatusCnt = Test.ulSensimStatusCnt + 1;`

 `send (TestNew);`
 `}`

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3.13 SensimFifo

Description The driver sends received data on the Sensim I/F in the block SensimFifo.

Declaration

```
typedef struct
{
    ULONG ulHwId;
    ULONG ulFifoId;
    ULONG ulLength;    // in ULONGs
    union
    {
        ULONG aul[SENSIM_FIFO_LENGTH];
        BITMAP 32 [64, 128] bmp;
    };
} tsSensimFifo;
```

Definition `blockdef tsSensimFifo tblkSensimFifo _SensimFifo;`

Example

```
decode on (_SensimFifo)
{
    switch (_SensimFifo.ulHwId)
    {
        case DFMS: // process DFMS data
            break;

        case RTOF: // process RTOF data
            break;

        case COPS: // process COPS data
            break;
    }
}
```

4 Commands

The GSEOS uses command channels for all commanding operations. The full description of the command channel architecture is given in the document “GSEOS Language Runtime Library Description” (IDA-GSEOS-0004).

Table 4 GSEOS Command Channels

Destination	Value	Channel Identifier	Description	
Internal	0x00ii0000	CMDCHANNEL_INTERNAL	ii	tbd
Hardware	0x01hhcc00	CMDCHANNEL_HARDWARE	hh	H/W identifier, depends on the project specific H/W driver
			cc	Command identifier, depends on the project specific H/W driver.
Serial	0x02ppww00	CMDCHANNEL_SERIAL	pp	The serial port (COMx:) number.
Network	0x03cc0000	CMDCHANNEL_NETWORK	cc	The network connection number.
File	0x04nn0000	CMDCHANNEL_FILE	nn	The file number.

4.1 Command Overview

The driver is able to process following commands:

Table 5 Command Overview

H/W Identifier	Command Identifier	Command Name	Parameter Bytes	
0	0	SelfStimulation	[0]	0 – off 1 – on
0	1	HwStart	[0]	0 – off 1 – on
1	0	TifLed	[0]	0 – LED green 1 – LED orange
			[1]	0 – off 1 – on

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H/W Identifier	Command Identifier	Command Name	Parameter Bytes	
2	0	AtifLed	[0]	0 – LED yellow 1 – LED green
			[1]	0 – off 1 – on
3	0	BtifLed	[0]	0 – LED blue 1 – LED green
			[1]	0 – off 1 – on
4	0	ScsimSendStatus	-	
	1	ScsimRegisterRead	[0..3]	0 – FPGA 1 – CIA
			[4..7]	register number
			out: [0..3]	value read
	2	ScsimRegisterWrite	[0..3]	0 – FPGA 1 – CIA
			[4..7]	register number
			[8..11]	value
	3	ScsimRegisterAnd	[0..3]	0 – FPGA 1 – CIA
			[4..7]	register number
			[8..11]	mask
	4	ScsimRegisterOr	[0..3]	0 – FPGA 1 – CIA
			[4..7]	register number
			[8..11]	mask
5	Scsim1355Write	[0..3]	bit 0/1: send eop1/eop2	
		[4..]	data (long)	
6	ScsimSciWriteTimingFifo	[0..]	data (byte)	
7	ScsimSciWriteCommand	[0..]	data (byte)	

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H/W Identifier	Command Identifier	Command Name	Parameter Bytes	
	8	ScsimSciTlmEnable	[0]	0 – off 1 – on
5	0	FesimSendStatus	[0..3]	0 – FESIM0 1 – FESIM1
			[4..7]	register number
	1	FesimRegisterRead	[0..3]	0 – FESIM0 1 – FESIM1
			out: [0..3]	value read
			[4..7]	register number
	2	FesimRegisterWrite	[0..3]	0 – FESIM0 1 – FESIM1
			[4..7]	register number
			[8..11]	value
	3	FesimRegisterAnd	[0..3]	0 – FESIM0 1 – FESIM1
			[4..7]	register number
			[8..11]	mask
	4	FesimRegisterOr	[0..3]	0 – FESIM0 1 – FESIM1
			[4..7]	register number
			[8..11]	mask
	5	FesimNWCmdSendHk	[0..3]	0 – FESIM0 1 – FESIM1
[4..]			data (byte)	
6	FesimNWCmdEnable	[0..3]	0 – FESIM0 1 – FESIM1	
		[4]	0 – off 1 – on	
7	FesimPMCmdSendHk	[0..3]	0 – FESIM0 1 – FESIM1	
		[4..]	data (bytes)	

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H/W Identifier	Command Identifier	Command Name	Parameter Bytes	
	8	FesimPMCcmdEnable	[0..3]	0 – FESIM0 1 – FESIM1
			[4]	0 – off 1 – on
	9	FesimNWImageWrite	[0..3]	0 – FESIM0 1 – FESIM1
			[4..]	data (long)
6	0	SensimSendStatus	-	
	1	SensimRegisterRead	[0..3]	register number
			out: [0..3]	value read
	2	SensimRegisterWrite	[0..3]	register number
			[4..7]	value
	3	SensimRegisterAnd	[0..3]	register number
			[4..7]	mask
	4	SensimRegisterOr	[0..3]	register number
			[4..7]	mask
	5	SensimFifoRead	[0..3]	H/W channel 0 –DFMS 1 –RTOF 2 –COPS
[4..7]			FIFO channel 0 –CMD 1 –HK 2 –SCI	
[8..11]			mode 0 – read FIFO 1 – read FIFO & update pointer 2 – dump	

H/W Identifier	Command Identifier	Command Name	Parameter Bytes	
	6	SensimFifoWrite	[0..3]	H/W channel 0 –DFMS 1 –RTOF 2 –COPS
			[4..7]	FIFO channel 0 –CMD 1 –HK 2 –SCI
			[8..11]	mode 0 – write FIFO 1 – write FIFO & update pointer

5 Registry Settings

The driver has some configuration settings in the registry. The user should never change the settings.


Because the driver is a Windows NT kernel mode driver the settings are stored in the registry. They can be found in the registry path:

HKEY_LOCAL_MACHINE\SYSTEM\CurrentControlSet\Services\GseRoset\Parameters

The table below describes the driver parameter:

Table 6 Registry Keys

Name	Type	Description
BreakOnEntry	DWORD	0 No INT 3 (debug breakpoint) on driver load. This is the default.
		1 Break in INT 3 (debug breakpoint) on driver load. The Windows NT Kernel Debugger must be present.
DebugLevel	DWORD	0 The driver generates no output on EventLog or Kernel Debugger.
		1 The driver generates EventLog output, but no Kernel Debugger output. This is the default.
		2 The driver generates EventLog and Kernel Debugger output, but no timing critical output.
		3 The driver generates full debug output including time critical output. This setting degrades the system performance.
HwBlkQueueLength	DWORD	The length of the block queue in bytes. Minimum: 10 times of the maximum block length in the driver plus 10 times sizeof (ULONG). Meaning the queue is minimum 10 blocks long. There is no maximum queue length. (limited by the system memory). The default is 1MByte.
SelfStimulationIntervall_ms	DWORD	Time Interval between generated blocks of type _SelfStimulationTicker in ms. The minimum is 1 ms, the maximum is 10000 ms. The default is 1000 ms.

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Name	Type	Description
SpareIoPortBase0	DWORD	not used
SpareIoPortBase1	DWORD	not used
SpareIrq	DWORD	not used
TifIoPortBase0	DWORD	The base address of TIF. The driver reserves an ISA I/O port range beginning with this address up to address + 0x60. The default is 0 (disabled).
TifIoPortBase1	DWORD	not used
TifIrq	DWORD	The ISA interrupt level of TIF. The default is 0 (disabled).